### **ASCENT Project 061**



Year 3: Rotor or small

□ Explore feasibility and

propeller-driven UAS Focus

applicability of current ASCENT

## **Noise Certification Streamlining**

### Georgia Institute of Technology

PI: Dimitri Mavris, Michael Balchanos

PM: Sandy Liu

Cost Share Partners: Boeing, Bell, Gulfstream, Rolls-Royce

Industry Partners: Boeing, Bell, Gulfstream, Rolls-Royce, Embraer, Cessna/Textron, De Havilland Canada

### **Objective:**

Examine current noise certification procedures and identify opportunities to streamline the noise certification process in addition to recommending methodologies for building the needed flexibility to accommodate all air vehicle types

### **Project Goal and Benefits:**

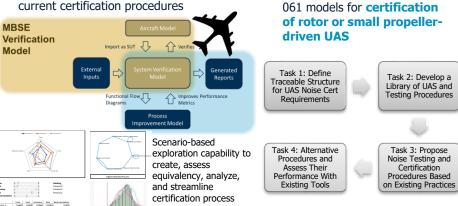
Recommendations towards efficient. а more streamlined, and flexible aircraft noise certification:

- Proposition of equivalent procedures, supported by latest technologies and hardware
- Evaluation of alternative practices through a Model-Based • Systems Engineering (MBSE) model of the noise certification process (in SySML)
- Analysis techniques to support certification of future air vehicles types

### **Research Approach**

#### Year 1,2: Transport **Category Focus**

Develop an MBSE-enabled noise certification model for benchmarking current certification procedures



### Major Accomplishments (to date):

- Key Improvements in SySML-based Verification Model
- Demonstrated the Process Improvement Model ٠ (PIM) for streamlined certification using Markov Chains
- Early version Visualization environment to provide ٠ oversight on EP and regulatory compliance
- Pivot to Rotor or small propeller-driven UAS ٠
- Benchmarking of current UAS noise certification (working with NPRM 86 FR 48281)

### Future Work / Schedule (Year 3 Tasks):

- Transport Category: Multi-scenario capability for exploration of equivalent procedures
- Complete ASCENT 61 UAS Noise Certification
  - Workshops with OEMs on rotorcraft and small UAS
  - Process prototyping with guidance by NPRM 86 FR 48281
  - Testing Equivalent procedures
- Findings & Recommendations for UAS Noise Certification

This research was funded by the U.S. Federal Aviation Administration Office of Environment and Energy through ASCENT, the FAA Center of Excellence for Alternative Jet Fuels and the Environment, Project 061 through FAA Award Number 13-C-AJFE-1 GIT-066, under the supervision of Sandy Liu, and Bill He. Any opinions, findings, conclusions or recommendations expressed in this this material are those of the authors and do not necessarily reflect the views of the FAA.

# ASCENT Project 061 Noise Certification Streamlining

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This research was funded by the U.S. Federal Aviation Administration Office of Environment and Energy through ASCENT, the FAA Center of Excellence for Alternative Jet Fuels and the Environment, Project 061 through FAA Award Number 13-C-AJFE-GIT-066, under the supervision of Sandy Liu, and Bill He. Any opinions, findings, conclusions or recommendations expressed in this this material are those of the authors and do not necessarily reflect the views of the FAA.

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## **Presentation Outline**

- Introduction
- Project Overview
  - The Team
  - ASCENT Project 61 3-Year Research Horizon
  - Noise Certification Framework for Transport Category and Application for UAS Configurations
- Part I: Improvements on MBSE Certification Framework for Transport Category
- Part II: Testing Framework for Noise Certification for UAS
- Conclusions and Next Steps

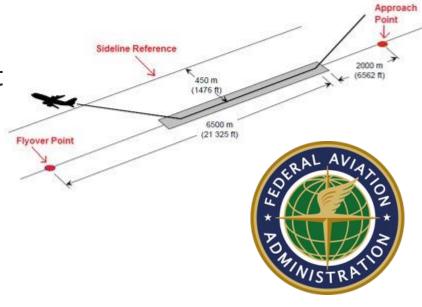
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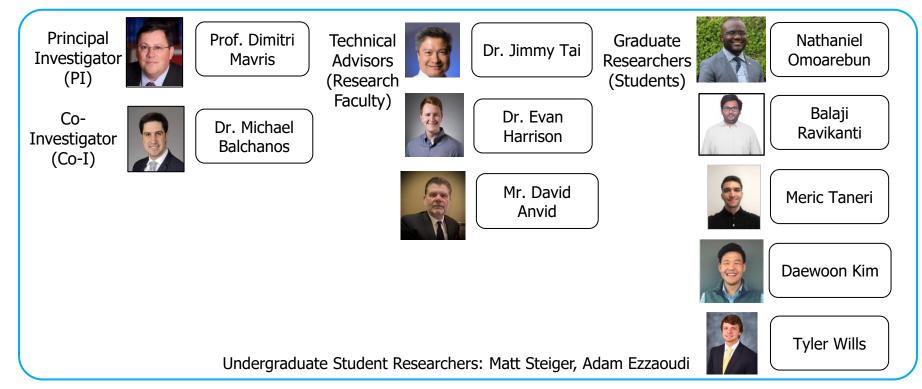






## **ASCENT 61 Team\***





\*The Georgia Tech ASCENT 61 Team would like to also acknowledge the contributions of the following past researchers: Fatma Karsten, Shireen Datta, Arnaud Ballande, Domitille Commun, Hayden Dean, Dr. Sehwan Oh and Dr. Etienne Demers Bouchard



## **ASCENT Project 61 Research** Horizon



**Objective**: Examine current noise certification procedures and identify opportunities to streamline by: 1) mitigating process bottlenecks, 2)addressing complexity, risk and uncertainty 3) ensuring transparency and repeatability



Aerospace Systems Design Laboratory Michael Balchanos, Ph.

## **Overview of Y2 to Y3 Direction: Noise Certification for UAS**



**The Ask**: Explore applicability of current ASCENT 061 models and analysis tools (based on transport category) for certification of rotor or small propeller-driven UAS

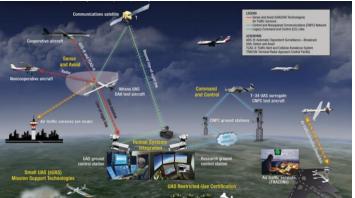
#### The Challenges:

- Large spectrum of UAS vehicles. Is our certification framework flexible to accommodate UAS?
- No general regulations. Application on case-to-case basis. Are current testing procedures effective for UAS?
- Assess and assist in iterating NPRMs for UAS Noise Certification Standards
- Address UAS before UAM (where risks are higher)

#### The Opportunities

- Test current procedures and assess flexibility of certification framework
- Initiate collaboration with ASCENT 077 researchers (PennState – Led by Prof. Eric Greenwood)
  - "Measurements To Support Noise Certification For UAS/UAM Vehicles And Identify Noise Reduction Opportunities"
  - Exchange of data and methods for noise measurements







# **Coordination: Parallel ASCENT Work**

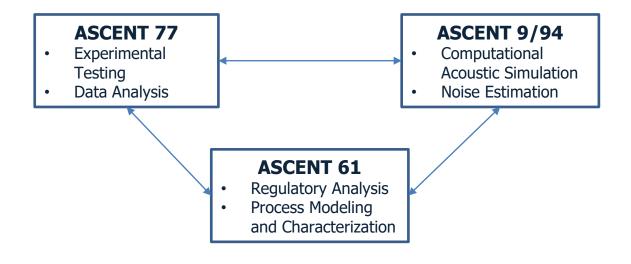


Currently there are 3 related, but unique ASCENT research efforts related to UAV/UAM noise.

- ASCENT 77 *Measurements to Support Noise Certification for UAS/UAM Vehicles and Identify Noise Reduction* Penn State University
- ASCENT 9/94 *Geospatially Driven Noise Estimation Module* Georgia Tech (ASDL)
- ASCENT 61 *Noise Certification Streamlining* Georgia Tech (ASDL)

To preclude "mission creep" into another projects remit, the Project 61 team is coordinating on a regular basis with Project 77 and Project 9/94 team members

- Data sharing: Experimental test data provides real world input to Noise certification modeling
- Comparison of mission profiles, certification profiles, and experimental testing field geometry Improves certification demonstration conditions

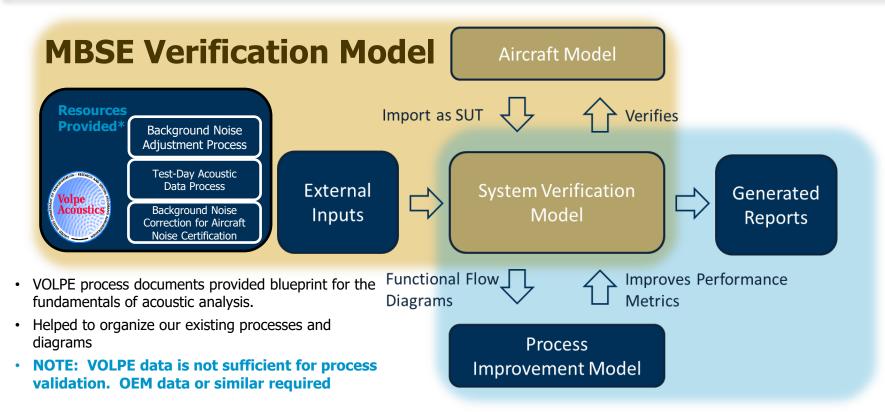




## Part I: Updates on MBSE-enabled Certification Process Assessment and Improvement Framework



**Goal**: Evaluate that potential alternative testing, measurement and analysis methods are acoustically conforming to regulatory standards



**Next Step:** Process Improvement Model (PIM) the tool set: Intended to provide quantitative guidance for process modification

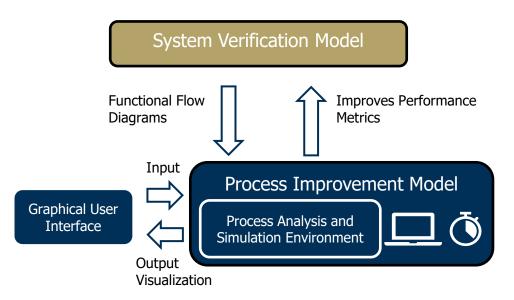
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VOLPE Resources\*: "Validation Protocol for Digital Audio Recorders User in Aircraft-Noise Certification Testing" [2010] "Audio Recording & Analysis System Validation Checklist" [2018] "Tort Data Acoustic Data Process" [2003]

"Test Data Acoustic Data Process" [2003] "Background Noise Adjustment Process" [2003]

# **Process Improvement Model (PIM)**



### The Process Improvement Model (PIM) is designed to represent and analyze the certification process for noise

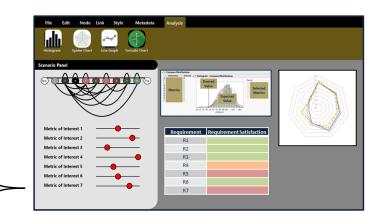
#### What does it do:

- Represents disjointed processes as a single chain of events
- Performs analysis of event chain

#### How does it do it?

- Graph theoretic approach to assess the efficiency, robustness, and complexity of the process chain
- Monte Carlo Markov Chain Simulation (MCMC) to analyze the performance of the events chain

### Graphical User Interface for Process Specification



- Provide visual representations of the process analysis outputs
- Provide critical metric information obtained from the process analysis
- Assess the equivalency of a procedure to standard regulatory practices

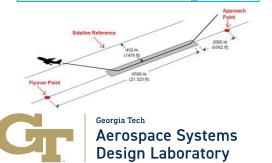


# **Evaluation Techniques in PIM**

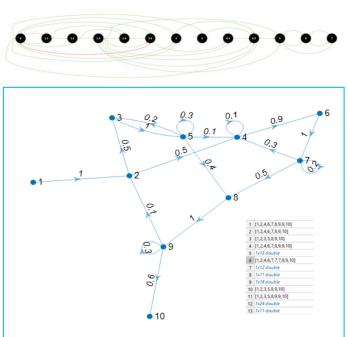


#### Define Test Day Data Process: Tests, recordings and SPL Analysis

8 C	D	E	F	G	н	
t-Day Acoustic Data Pro						
t Adjustmen	t & Reconstructio	n of Test-Day SP	LS .		1.0	
1 Step	Perform Par	Perform Part 1 of Background Noise Adjustment Procedure: Identify Masked Dat				
Input	1/3-Octave:	1/3-Octave spectrum: Pre-Detection Levels				
Input	1/3-Octave:	1/3-Octave spectrum: Post-Detection Levels				
Input	Spectral Tim	Spectral Time-History: Aircraft Noise SPLs				
input	1/3-Octave 1	1/3-Octave Spectrum: Combined System Corrections				
Output	Spectral Tim	Spectral Time-History: Map of Masked Aircraft Noise SPLs				
Output	Time-History	Time-History: LGBs				
Output	Spectral Tim	Spectral Time-History: Adjusted Valid Aircraft SPLs				
	11 Sub-Step	Test Validity of each Pre-Detection Level vs Post-Detection Level				
	Input	1/3-Octave spectrum: Pre-Detection Levels				
	Input	1/3-Octave spectrum: Post-Detection Levels				
	Output	1/3-Octave:	spectrum: Valid Pr	e-Detection Leve	els	
		Action	Determine val	idity of pre-dete	ction level vs. pos	
			Specification	Pre-detection	level is valid only	
	1.2 Sub-Step	Determine N	<b>Masking Criterion</b>	or each 1/3 oct	ave band	
	Input	1/3-Octave spectrum: Post-Detection Levels				
	Input	1/3-Octave spectrum: Valid Pre-Detection Levels				
	Output	1/3-Octave spectrum: Masking Criteria				
		Action	Determine ma	sking criterion f	or each 1/3-octav	
			Specification	For each 1/3-	octave band, the m	
				The valid pre-	detection level plu	
1				The post-deter	tion level plus 1 a	
	1.3 Sub-Step	Test each aircraft SLP vs masking criterion to determine validity				
	Input	1/3-Octave spectrum: Masking Criteria				
	Input					
	Output					
	Output	Time-History: LG8s				
		Action Compare the aircraft SPL to the masking criter				
		Action	Determine LGB	for each spectr	al record	
			Sub-Action	Increment the	band number star	
			Sub-Action	Set LGB to the	band below the m	
				Specification	Assumption: On	
	1.4 Sub-Step	Decombine Valid Pre-Detection Level from Valid Aircraft SPL				
	Input	1/3-Octave spectrum: Valid Pre-Detection Levels				
	Input	Spectral Time-History: Map of Masked Aircraft Noise SPLs				
	Input	1/3-Octave	1/3-Octave spectrum: Masking Criteria			
	Output	Spectral Time-History: "Decombined" Valid Aircraft SPLs				
		Action Decombine the pre-detection noise energy from				
			Specification	SPLbgad) = 10	log[ 10*(SPLac *0.	
				Where:	1990 - 1990 - Inc.	
				SPLbgad) is th	e background-ad)	
					lid aircraft level	
					alid pre-detection	
	1.5 Sub-Step	Add Combin	ed System Correct			
	Input		e-History "Decom			
		input Spectral Time-History: Map of Masked Aircraft Noise SPLs input 1/3-Octave Spectrum: Combined System Corrections				
	Output	Spectral Time-History: Adjusted Valid Aircraft SPLs				
		Action			measurement cor	
		(Charles and a	Specification		ent for pre-detection	
			apresident and		ncy-response (pin	
				Windscreen in	ressure-field & fro	



Represent Process as Event Chain and Graph Model and Analyze using Graph Theory



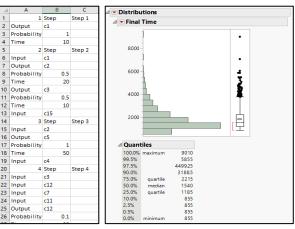
## Goal: Analyze complexity of the process as well as identifying potential bottlenecks

Use a Weighted Directed Graph:

- Each node represents a step in the process
- Edges represent transitions between steps
- Progression through the steps is represented by probabilities and parameters at each step

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#### Analyze Process through Probabilistic MCMC Simulation



## Early "Monte Carlo Markov Chain" (MCMC) algorithm steps:

- 1. Start from a node
- 2. "Roll dice" (generate a random number)
- 3. Depending on the outcome, and the probability of each path, the algorithm selects the next node
- 4. Learning factor is utilized to update probabilities of progressing through the steps (increased probability the second time)

#### **Tracking Metrics:**

- Time and Cost for completing process
- Complexity/Uncertainty-driven error propagation

# **PIM Demonstration Use Case**

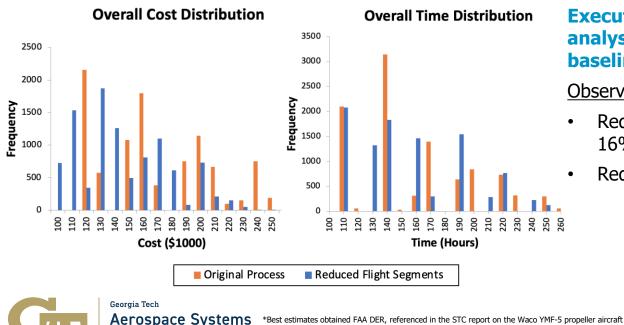


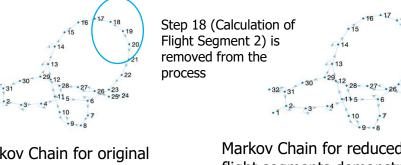


### PIM demonstration on assessing a simplified noise collection/analysis process for Waco YMF-5 propeller aircraft

- The baseline (original) process was formulated within the PIM and executed using best\* estimates for times and cost
- The simplified process removes step 18 (calculation of the second flight segment) while other steps were updated with new values to capture the updated process

**Design Laboratory** 





Markov Chain for original process

Markov Chain for reduced flight segments demonstration

**Execution of MC-based Monte Carlo** analysis and comparison between baseline and simplified process

#### **Observations**

- Reduction of average process cost by 16%
- Reduction of average process time by 2%

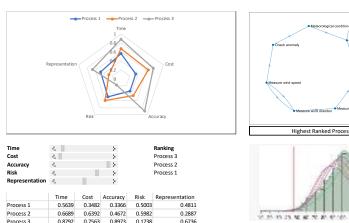
		Mean
<b>Original</b>	Cost(\$)	166,770
	Time(hrs.)	155
Reduced	Cost(\$)	140,430
<u>Segments</u>	Time(hrs.)	151

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# **Conceptual Visualization Environment**



Early implementation of a Minimum Viable **Product (MVP) for** the visualization environment



## Current capabilities of the environment include:

- A spider chart to display the means of multiple metrics for multiple processes
- The highest ranked process as a chain of events
- Selection of distributions for multiple metrics
- The mean values of distributions
- Slider-bars to adjust the desirability of criteria

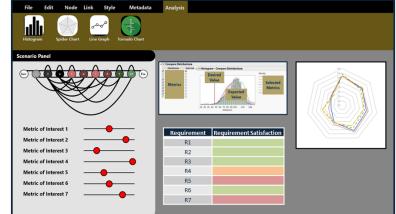
**End Goal:** An interactive and user-friendly capability to create, assess equivalency, analyze, and streamline certification process

Highest Ranked Process

Cold Shield day



Representation of the envisioned visualization environment



## Part II: MBSE Noise Certification for UAS: Planning the framework transition process

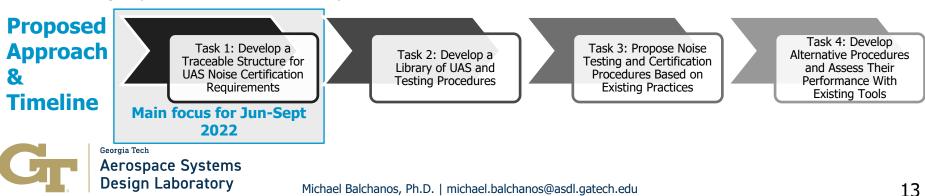


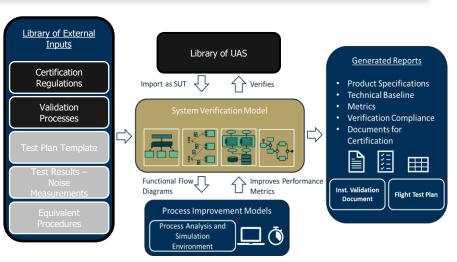
**The Ask**: Explore feasibility and applicability of current ASCENT 061 models for certification of rotor or small propeller-driven UAS. **The Goals** are:

- Track and ensure traceability between regulations, testing requirements and certification procedures
- Demonstrate feasibility of NPRMs, recommend testing procedures for UAS noise certification

### **Observed Challenges:**

- No clear regulatory framework
  - Study will rely on NPRMs, Appendices G, J, and H of CFR Title 14 Part 36
- No clear categorization of UAS
  - Study will propose criteria, e.g., weight; propeller no./type/orientation; flight envelope; max speed; operational altitude]
- No test data immediately available
  - $\circ~$  Study will rely on test plan information, test day logs, and available/sharable noise data by ASCENT77
- No established validation process against regulationdriven requirements
  - Study will track/ensure traceability between regulations, testing requirements and certification procedures





#### Modified ASCENT 61 Certification Process Model for UAS

## **Task 1: Analyze Regulatory Requirements Analysis Process**



**Objective**: Analyze proposed noise test procedure requirements for suitability to UAS category vehicles and understand sensitivity of noise to the operational flight parameters





Gather Supporting Data



- Noise Level Classification
- Vehicle/Operational Classification
- Noise Metrics
- Testing Framework: Flight Profiles, SUT Configurations, Measurements



Part 36 Appendix J covers alternative noise certification procedure for helicopters (under Subpart H) having a *maximum certificated takeoff weight of not more than 7,000 Pounds* 

\*\*Matternet noise standard final rule was published in September 2022



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#### What to look for:

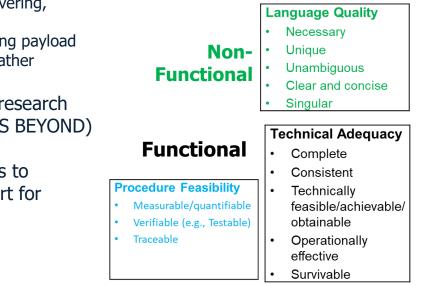
- Test data and insights by the ASCENT 77 group
  - Octocopter (Tarot X8) measurements for Hover Vertical Takeoff and Landing, Flyover, Maneuvering, Approach/Climb
  - Tests conducted at varying payload weights, speeds and weather
- Academic or industrial research literature (e.g., FAA UAS BEYOND)
- Noise prediction models to generate data in support for requirements analysis



Requirements Analysis

#### How is it performed:

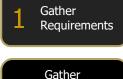
Use of obtained test data and leveraging functions within the MBSE certification framework, and the following criteria:



\*NPRM 86 FR 48281 (September 2021): https://www.federalregister.gov/documents/2022/09/12/2022-19639/noise-certification-standards-matternet-model-m2-aircraft Matternet Noise Standard (September 2022) : https://www.regulations.gov/document/FAA-2021-0710-0016 [1] US Department of Defense Systems Engineering Guidebook Section 4.2.7

## Example Case Study: NPRM 26(b) Feasibility

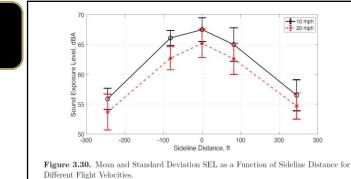


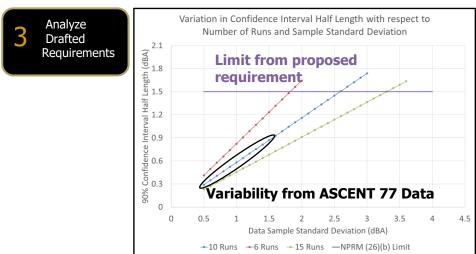


Data

Supporting

**NPRM - 26(b):** The minimum sample size acceptable for the aircraft flyover certification measurements is six. The number of samples must be sufficient to establish statistically a 90 percent confidence limit that does not exceed  $\pm 1.5 \, dB(A)$ .





- Total of 10 runs over two different days
- Range: 0-5 knots.
- Sample Standard deviation: 0.6dBA

#### Data [1] represents natural variability in UAV operational noise measurements

### Does experimental data provide evidence that the proposed requirement is technically feasible?

### Analysis of gathered data (by ASCENT 77)

- Map flight test count to observed variability
- Extrapolate variability for varying flight test count

#### **Observations**

- Negatively correlated: More flight tests, less noise measurement variability
- All observations well within proposed variability • requirement: Not exceeding  $\pm 1.5 dB(A)$ Conclusion
- The proposed requirement NPRM 26(b) is technically feasible



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[1] Konzel, N. B Ground based measurements and acoustic characterization of small multirotor aircraft. Masters Thesis. 2022.

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## **Summary**



**Year 2 Progress:** ASCENT 61 Team has completed the architecting of a noise certification modeling and assessment framework for transport category aircraft

- Informed by input (training materials and data) provided by VOLPE and OEMs
- Analysis enabled by a probabilistic Process Improvement Model (PIM), which is key for process assessment and evaluation, while experimenting with Equivalent Procedures
- Demonstration through assessing a simplified noise collection/analysis process for Waco YMF-5 propeller aircraft (15% reduction on average costs, 2% reduction on average time required)
- Next Steps [Transport Category Tasks]:
  - Add capability for scenario-based experimentation with recommendations for Equivalent Procedures (EP) provided by OEMs
  - Demonstration of EP assessment and prioritization in an interactive decision support environment

**Project Scope Pivot for Year 3:** Explore applicability of current ASCENT 061 models and analysis tools (currently based on transport category) for certification of rotor or small propeller-driven UAS

- Background and literature search on current noise certification practices for UAS
- Process for repurposing the ASCENT 61 MBSE Noise Certification Framework for UAS Category, to provide oversight on EP and regulatory compliance
- Analysis and assessment on the NPRM 86 FR 48281
- Next Steps [UAS Category Tasks]:
  - Update PIM and noise analysis modules
  - Demonstration of noise certification based on NPRM 86 FR 48281
  - Demonstration of EP assessment through certification modeling across different UAS configurations

#### **Publications**

- Kim, D., Karagoz, F., Datta, S., Balchanos, M., Anvid, D., Harrison, E., and D.N. Mavris (2022). A Model Based Systems Engineering Approach To Streamlined Noise Certification Of Transport-type Aircraft. In 33rd Congress of International Council of the Aeronautical Sciences ICAS, Stockholm, Sweden, 2022.
- Kim, D., Taneri, M., Omoarebun, E., Balchanos, M., and Mavris, D. (2023). MBSE-Enabled System Verification and Process Improvement of Transport Aircraft Certification. Accepted and to be presented In AIAA SciTech 2023 Forum, National Harbor, MD, January 23-27, 2023.



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## **Questions? Comments?**

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